SAFERIDE

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ביה"ס למדעי המחשב ע"ש בלווטניק

הפקולטה למדעים מדויקים ע"ש ריימונד ובברלי סאקלר אוניברסיטת תל אביב



TAU CS 0368-3527-01 IoT Workshop, Spring 2019 Sivan Toledo and Nir Levi

OUTLINE



The problem



The product



The purpose



App Demo



How does it work

THE PROBLEM

- Electric bikes, nowadays, are used vastly, by all ages
- There is limited monitoring (if any)
 - Increasing number of accidents among teenagers
 - Increasing number of death cases among teenagers
- Popularity gains: cheaper bikes and better infrastructures (hopefully)

STATISTICS

- Number of casualties rises;
 - 2015-692
 - 2018-2185
- Number of deadly accidents rises
 - 2015- 2 deaths
 - 218- 18 deaths (4 under 16)



DEMO VIDEO

https://youtu.be/IQ-5QJiAupc

THE PRODUCT - COMPONENTS

Hardware

- The device consists of Adafruit Feather 32u4 Bluefruit LE board.
- Battery usage, Activate bike battery
- Accelerometer based on phone (fall back): identify falls

Software

Xamarin based app

Arduino libraries

Azure cloud services

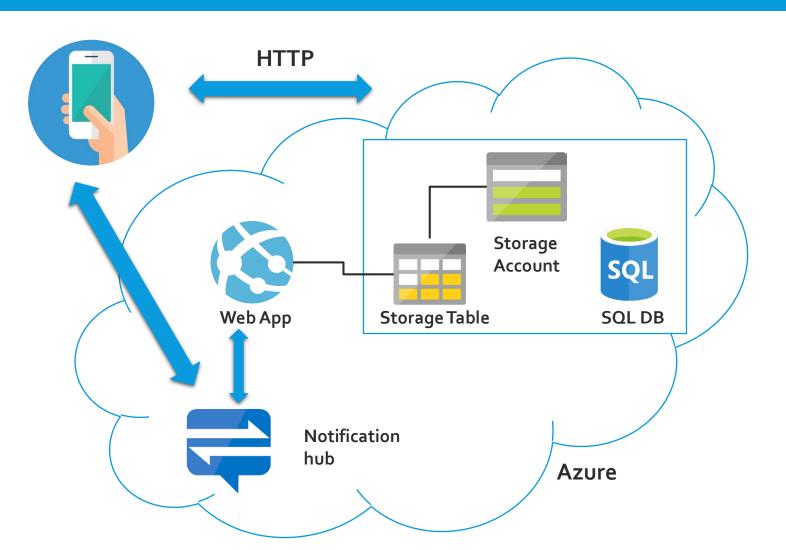
HOW DOES IT WORKS - WORKFLOW





Bluetooth Connection



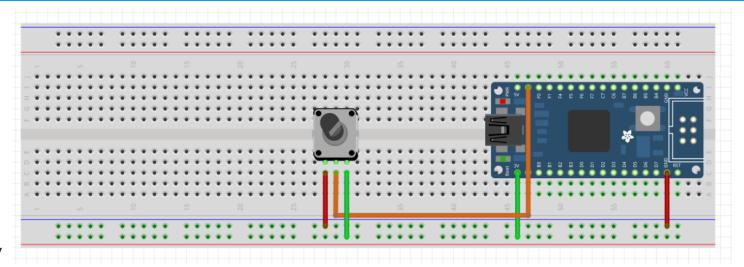


HARDWARE – THE PARTS

Adafruit Bluefruit 3204

Bulb

Mock on/off of the battery



Potentiometer

Mock the voltage inside the battery

* BLE CONNECTION

Using UART service.

• **UUID**: 6E400001-B5A3-F393-E0A9-E50E24DCCA9E

UART connection

The service simulates basic UART connection over two lines; TX and RX

The service include two characteristics:

- TX (oxooo2) written to by the connected Central device.
- **RX (oxooo3)** used to send data from the peripheral device to the connected Central device.

* BLE CONNECTION

Central device scans for Bluetooth low-energy device.

• Blinking Red Led symbols BLE existence.

Connects to our Arduino device

- recognizable by unique prefix name
- Blue Led lights when connection established

Central Device invokes event

• listening to data send from the arduino device (battery percentage change).

Upon start/end ride

• central device sends turn on/off bike instruction to the peripheral device, respectfully.

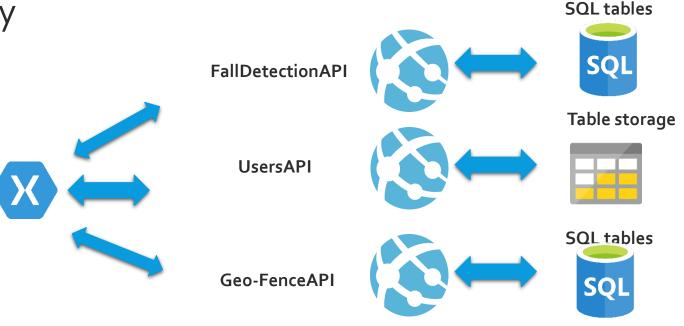
HOW DOES IT WORK – MICRO SERVICES

Each micro-service is:

- Independent functionality
- Independent DB
- Independently deployable

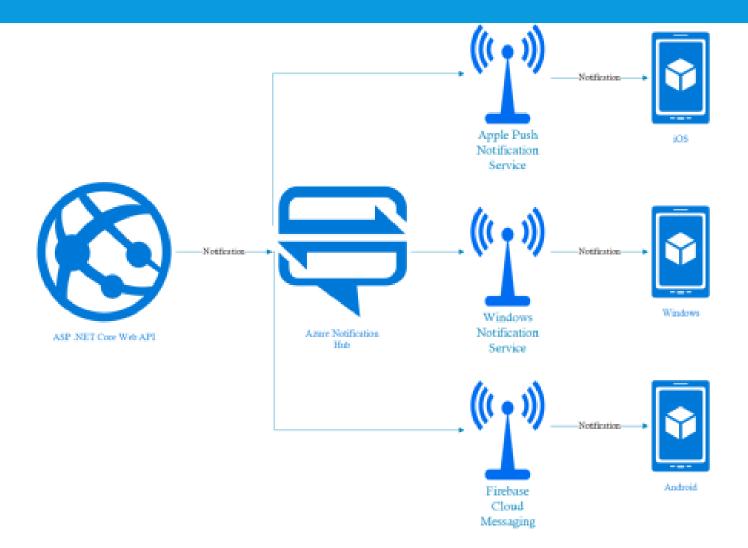
Allows:

- Easy maintenance
- Simplicity
- Fast development



NOTIFICATIONS

- To the "Parent" (admin)
- When fall detected
- When exiting the geofence



SERVICES OUTLINE







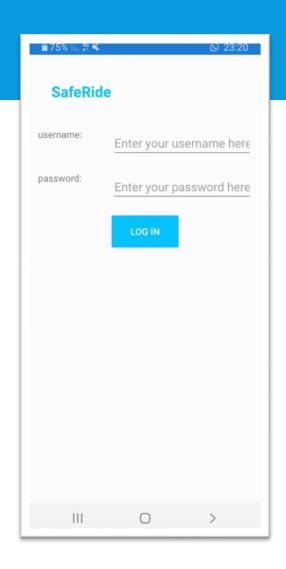






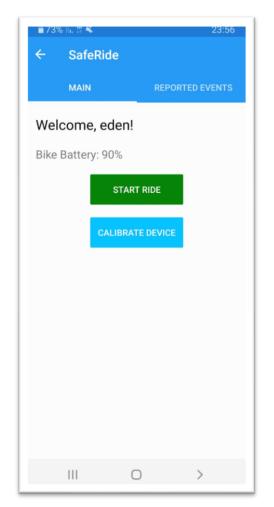
USERS MANAGEMENT

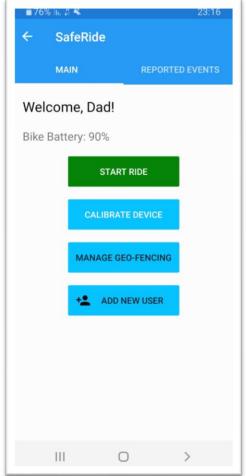
- Multiple users can use the same device
- "Parent" (Admin) users
- First Login (no users associated to current device ID) creates new user with admin privileges.
- Login management:
- Server Data Base
- Hashed Passwords transmitted (SHA-256)

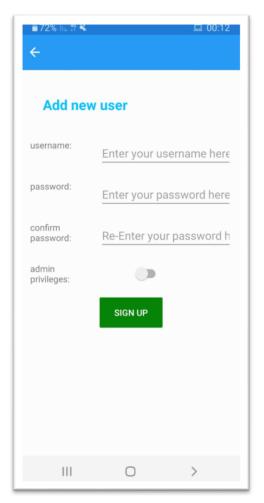


USERS API

- Manages user's tables
- Authorization
- Licenses







USERS API - JSONS

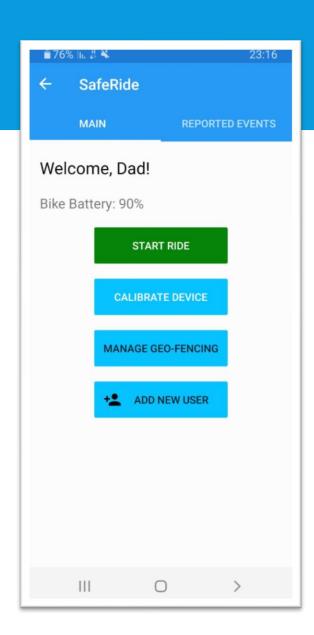
USERS API - TABLES

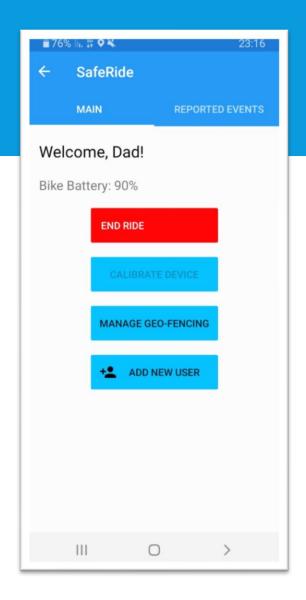
PARTITIONKEY^	ROWKEY	TIMESTAMP	ISADMIN	PASSWORD
123	Dad	2019-06-23T07:22:12.9064153Z	true	03ac674216f3e1
123	Son	2019-06-26T15:26:49.0486079Z	false	98aa6675482552
123	eden	2019-06-26T11:44:42.3513816Z	false	e24ef8f9382887



SMART LOCK

- Enable engine via application
- Multiple users
- No need for a key

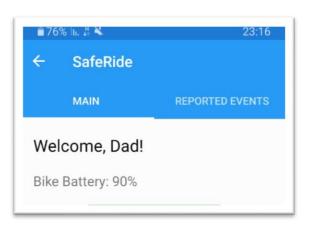




BUTTERY USAGE

- User cab see the buttery percentage
- //Supply estimated distance according to percentage



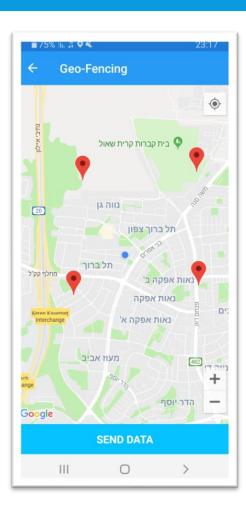


GEOFANCE



Safety

• Limits riding area



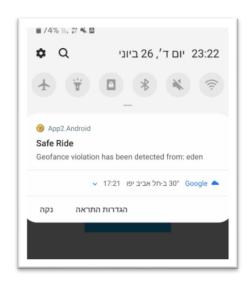
Hardware

Device GPS service

Cloud

- SQL DB
- API
- Notification

Algorithm



GEOFANCE API

- StartRide/SaveRiderPlot/FinishRide/SaveRiderGeoFancePlots
- Uses
 - Google maps API
- Logics:
 - Geofence geometry of space
 - Notifications
 - Rides summary distance, average speed, etc

GEOFANCE API-JSONS

StartRide

```
1 * {
2     "UserId":"1",
3     "RiderGeoFanceId":"25",
4     "Latitude":32.106534,
5     "Longitude":34.797006
6 }
```

SaveRiderPlot/FinishRide

```
1 + {
2     "RideId":"172",
3     "Latitude":-72.2827005,
4     "Longitude":42.9272685,
5     "Time":"2019-06-10 19:49:59.010"
6 }
```

SaveRiderGeoFancePlots

GEOFANCE API-TABLES

	Rideld	Userld	RiderGeoFanceId	StartTime	EndTime	Distance	AverageSpeed	IsInsideGeofance
140	176	3	26	2019-06-26 08:27:37.523	2019-06-26 08:28:17.920	0.32	28.67	1
141	177	3	26	2019-06-26 08:29:32.700	2019-06-26 08:30:27.920	0.15	10.20	1
142	178	3	26	2019-06-26 08:30:57.730	2019-06-26 08:31:32.930	0.16	16.89	1

	Userld	PlotsId	PlotsJson
1	1	2	[{"Longitude":42.9284076,"Latitude":-72.2778296},{"Longitude":42.9270878,"Latitude":-72.28698
2	1	3	[{"Longitude":42.9284076,"Latitude":-72.2778296},{"Longitude":42.9270878,"Latitude":-72.28698
3	1	5	[{"Longitude":42.9284076,"Latitude":-72.2778296},{"Longitude":42.9270878,"Latitude":-72.28698
4	1	7	[{"Longitude":42.9284076."Latitude":-72.2778296}.{"Longitude":42.9270878."Latitude":-72.28698

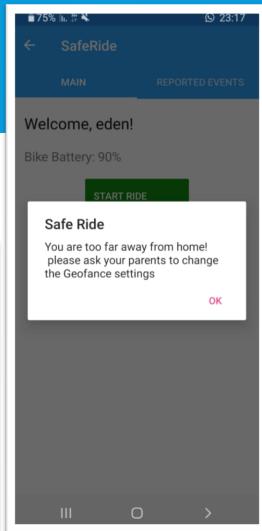
	RidePlotId	Rideld	Longitude	Latitude	Time	IsInsideGeoFance
1	1	1	42.92810900	-72.27818370	2019-05-25 10:41:53.953	1
2	2	1	42.92749630	-72.28076930	2019-05-24 11:35:45.617	1
3	3	1	42.92726850	-72.28270050	2019-05-22 09:47:59.010	1
4	4	2	42.92810900	-72.27818370	2019-05-25 05:16:28.887	1

GEOFANCE API-ALGORITHM

Is point inside polygon?

```
    RiderWebAPI.Controllers.rideController

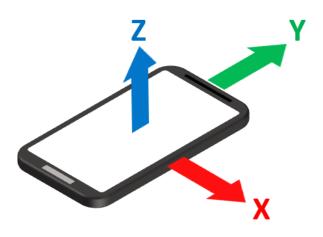
¬ SpointInPolygon(List<Location> poly, Location → SpointInPolygon(List<Location → SpointI
                                                     public bool CheckInsideGeoFance(int RideId, decimal Latitude, decimal Longitude)
                                                                 Location point = new Location { Latitude = Latitude, Longitude = Longitude };
                                                                UserRide userRide = riderappEntities.UserRides.Find(RideId);
                                                                RiderGeofancePlot rp = riderappEntities.RiderGeofancePlots.Find(userRide.RiderGeoFanceId);
                                                                List<Location> poly = Newtonsoft.Json.JsonConvert.DeserializeObject<List<Location>>(rp.PlotsJson);
                                                                return IsPointInPolygon(poly, point);
                                                     private static bool IsPointInPolygon(List<Location> poly, Location point)
                                                                 int i, j;
                                                                 for (i = 0, j = poly.Count - 1; i < poly.Count; j = i++)</pre>
                                                                                        ((poly[i].Latitude <= point.Latitude) && (point.Latitude < poly[j].Latitude)) |
                                                                                        ((poly[j].Latitude <= point.Latitude) && (point.Latitude < poly[i].Latitude)))</pre>
                                                                                       (point.Longitude < (poly[j].Longitude - poly[i].Longitude) * (point.Latitude - poly[i].Lat
                                                                 return c;
                                                     private double GetDistanceBetweenLocations(Location location1 , Location location2)
                                                                 double rlat1 = Math.PI * (double)location1.Latitude / 180;
```



FALL DETECTION

Safety

Alert device users

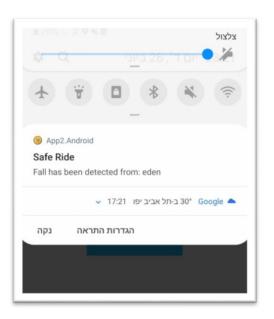


Hardware

Phone 3- axis accelerometer

Cloud

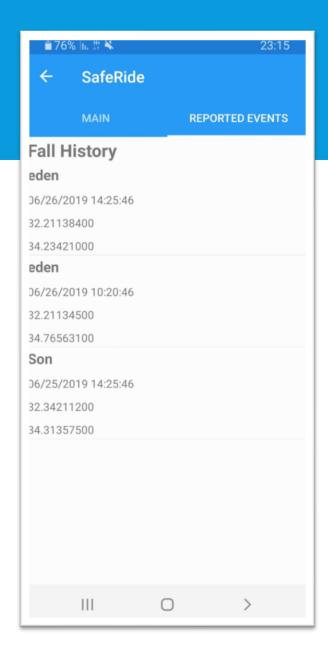
- SQL DB
- API
- Notification



Algorithm

FALL DETECTION API

- Analyze Accelerometer data
- Calibration
- Handles SQL database
- Users History



FALL DETECTION API - JSONS

```
1 + {
                                                                     Safe Ride
     "DeviceId": "123",
                                                                     Calibration succeeded:)
     "UserId": "DAD",
     "XData": 0.9,
     "YData": 0.08,
     "ZData": 0.15,
     "Time": "2019-06-26T17:03:49.7503776+00:00",
     "Latitude": 32.012321,
     "longitude": 34.304213
10
                                      "DeviceID": "1234",
                                      "CalibrationX": 0.02,
                                      "CalibrationY": 0.1,
                                      "CalibrationZ": 0.92
```



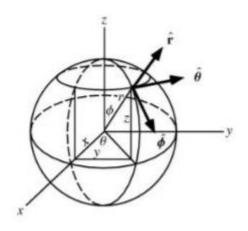
FALL DETECTION API - TABLES

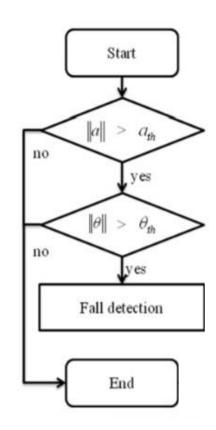
DeviceID	CalibrationX	CalibrationY	CalibrationZ
123	0.04	0.13	0.931
1234	0.02	0.1	0.92

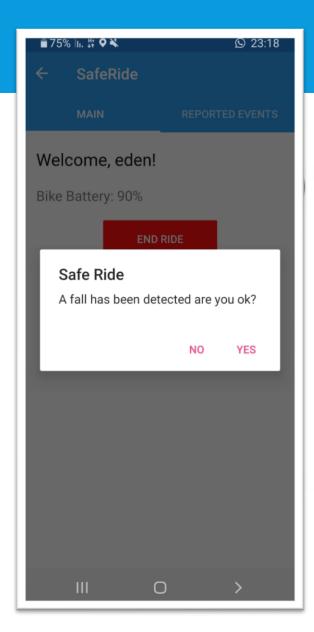
	fallDetecionID	deviceID	userID	timeStamp	latitude	longitude
1	479	123	eden	2019-06-26 14:25:46.207	32.21138400	34.23421000
2	480	123	Son	2019-06-25 14:25:46.207	32.34211200	34.31357500
3	481	123	eden	2019-06-26 10:20:46.207	32.21134500	34.76563100

FALL DETECTION API - ALGORITHM

Fall detecting algorithm







THOUGHTS AHEAD

- Gyroscope more accurate fall detection
- SMS service
- Emergency service
- Multithreaded allows falls detections and
- Performance